



### Personal information

Surname(s) / First name(s)  
Address(es)  
Telephone(s)  
Email(s)  
Nationality(-ies)  
Date of birth  
Gender

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[gionata.salvietti@unisi.it](mailto:gionata.salvietti@unisi.it)  
Italian  
22 July 1983  
Male

### Summary of Experience

- Published researcher with 15+ years of experience in robotics and 90+ scientific publications.
- Associate Editor for IEEE Transaction on Robotics and IEEE Transaction on Haptics.
- Organization of workshops at top robotics conferences and of special issues in top robotics journals.
- Co-developer of SynGrasp, a Matlab toolbox for robotic grasping analysis that has overcome 9000 downloads
- Supervisor of Researchers (Assegnista di ricerca) at the Department of Information Engineering and Mathematics, University of Siena
- Coordinator for the University of Siena Unit of the European Erasmus+ project “Immersive SurgicalEdu” and the Italian MUR PRIN project “ARTIS”.
- Principal Investigator for the European Erasmus+ project AugmentedWearEdu and Immersive Surgical Edu and Work-package leader in five EU projects.
- Activity Leader in the project Fit4MedRob - Fit for medical Robotics, financed by the Italian Ministry of Research.
- Member of the “Commissione per l’orientamento” from 2022.
- Lecturer for the Courses on Control Systems and Industrial Robotics at the Department of Information Engineering and Mathematics of the University of Siena

### Education #1

National Scientific Qualification

From 20 November 2023 **qualified as Full Professor “Professore Ordinario”** in the Italian higher education system in the call 2021/2023 (Ministerial Decree n. 553/2021) for the disciplinary field of 09/G1 - Systems and control engineering. (Academic Recruitment Field 09/G - Systems engineering and bioengineering, according to the national classification).

Dates  
Title of qualification awarded  
Name and type of organization providing education and training  
Thesis title

October 2009 - November 2012  
**PhD on Information Engineering** research track **Automatic control and Robotics**  
Department of Information Engineering and Mathematics, University of Siena, Italy

Dates  
Occupation or position held  
Main activities  
Name and type of organization

**An Object-Based Approach to Map Human Hand Synergies onto Robotic Hands with Dissimilar Kinematic**  
  
April 2009 - September 2009  
**Visiting student**  
Research on Teleoperation and Haptics in the context of the **European Project ROBOCAST**  
Department of Information Engineering and Mathematics, University of Siena, Italy

Dates	October 2006 - April 2009
Title of qualification awarded	<b>“Laurea Specialistica”</b> on Computer Science Engineering, “cum laude”
Name and type of organization providing education and training	Department of Information Engineering and Mathematics, University of Siena, Italy
Thesis title	<b>Task Priority Grasping and Locomotion Control of Modular Robot</b>
Dates	October 2002 - July 2006
Title of qualification awarded	<b>“Laurea”</b> in Automation Engineering
Name and type of organization providing education and training	Department of Information Engineering, University of Siena, Italy
Thesis title	<b>Il Robot SBPP 3000: Sviluppo di Circuiti per il Controllo</b>
Dates	January 2001 - December 2002
Title of qualification awarded	Head of Industrial Automation Systems and Robotic
Principal subjects	Professional training
Name and type of organization providing education and training	Department of Information Engineering, University of Siena, in collaboration with <b>European Community</b> and <b>Tuscany Region</b>
<b>Appointments #2</b>	
Dates	From November 2022
Occupation or position held	<b>Associate Professor</b>
Main activities	<ul style="list-style-type: none"> <li>• Research on human-centered robotics, robotic sensorimotor augmentation, medical and assistive robotics, haptics, robotic and human grasping.</li> </ul>
Name and type of organization	Department of Information Engineering and Mathematics, University of Siena, Italy
Dates	From March 2016
Occupation or position held	<b>Research Affiliate</b>
Main activities	<ul style="list-style-type: none"> <li>• Research on manipulation with soft hands, advanced sensing for industrial application, telemanipulation, robotic and human grasping</li> </ul>
Name and type of organization	Center for Robotics and Intelligent Systems, Humanoids & Human Centered Mechatronics group, Istituto Italiano di Tecnologia, Italy
Dates	From November 2019 to November 2022
Occupation or position held	<b>Assistant Professor, RTD - B</b>
Main activities	<ul style="list-style-type: none"> <li>• Research on human-centered robotics, medical and assistive robotics, haptics, robotic and human grasping.</li> </ul>
Name and type of organization	Department of Information Engineering and Mathematics, University of Siena, Italy
Dates	From March 2016 to November 2019
Occupation or position held	<b>Assistant Professor, RTD - A</b>
Main activities	<ul style="list-style-type: none"> <li>• Research on intelligent robotics, human-centered robotics, medical and assistive robotics, robotic and human grasping in the context of the EU projects <b>SoftPro</b> and <b>WEARHAP</b>.</li> </ul>
Name and type of organization	Department of Information Engineering and Mathematics, University of Siena, Italy
Dates	From April 2015 to February 2016
Occupation or position held	<b>PostDoc at University of Siena</b>
Main activities	<ul style="list-style-type: none"> <li>• Research on medical robotics, robotic grasping and teleoperation.</li> <li>• Support in the realization of the massive on-line course “The art of grasping” financed by Mathworks.</li> </ul>
Name and type of organization	Department of Information Engineering and Mathematics, University of Siena, Italy
Dates	October 2012 - March 2015

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Occupation or position held Main activities	<b>PostDoc at Istituto Italiano di Tecnologia</b> <ul style="list-style-type: none"> <li>Theoretical and practical experience on teleoperation, human and robotic hand grasping and medical robotic applications.</li> <li>Development of the Matlab toolbox SynGrasp a tool for robotic grasping analysis that has overcome 6000 downloads.</li> <li>Active participation to four EU Integrated Projects: ACTIVE (robotic brain surgery), The Hand Embodied (robotic hand control and design), WEARHAP (wearable haptics) and HANDS.DVI (control of robotic hands).</li> </ul>
Name and type of organization	Department of Advanced Robotics, Istituto Italiano di Tecnologia (IIT), Genova, Italy
Dates	June 2012 - September 2012
Occupation or position held Main activities	<b>Visiting Researcher at Deutsches Zentrum für Luft- und Raumfahrt (DLR)</b> <ul style="list-style-type: none"> <li>Research on human-inspired control of robotic hands through mapping algorithm and implementation of new algorithms for the control of the DLR Hand II.</li> <li>Software development for Matlab/Simulink environment and the Real-Time Workshop (RTW).</li> <li>Software development for the DLR Hand II, which is a complex mechatronic system with 12 motors and about 100 sensors.</li> </ul>
Name and type of organization	Institute for Robotics and Mechatronics, Deutsches Zentrum für Luft- und Raumfahrt (DLR) - Oberpfaffenhofen, Germany.
Dates	July 2008 - January 2009
Occupation or position held Main activities	<b>Visiting student at TAMS Lab, University of Hamburg</b> <ul style="list-style-type: none"> <li>Research on modular robot as grasping devices.</li> <li>Development of a grasping application for a modular snake-like robot.</li> <li>Development of hierarchical control framework based on task-priority.</li> <li>Development of a simulation environment based on <i>C++</i> using ODE and OpenGL libraries.</li> </ul>
Name and type of organization	<b>Department of Informatics, TAMS Lab (Technical Aspects of Multimodal Systems), University of Hamburg, Hamburg, Germany</b>
<b>Teaching Experience</b> <b>#3</b>	
Dates	2023 - today
Occupation or position held Main activities	<b>Lecturer</b> Teaching the <b>Industrial Robotics</b> class
Name and type of organization	Department of Information Engineering and Mathematics, University of Siena, Italy
Dates	2019 - today
Occupation or position held Main activities	<b>Lecturer</b> Teaching the <b>Control Systems</b> class
Name and type of organization	Department of Information Engineering and Mathematics, University of Siena, Italy
Dates	2020 - today
Occupation or position held Main activities	<b>Lecturer</b> Teaching the <b>Advanced Manipulation Systems</b> class
Name and type of organization	First Level Master on Industry 4.0 design, University of Pisa, Italy
Dates	June 2021
Occupation or position held Main activities	<b>Lecturer</b> Teaching the <b>Robotic Teleoperation</b> class
Name and type of organization	Phd School in Information engineering and Science, University of Siena, Italy
Dates	August 2019 - September 2019

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Occupation or position held Main activities Name and type of organization	<b>Lecturer</b> Teaching in the <b>From Robotic Grasping Theory to Soft Manipulation</b> class Harbour.space University, Barcelona, Spain.
Dates Occupation or position held Main activities Name and type of organization	2016 - 2019 <b>Lecturer</b> Co-Teaching in the <b>Robotics</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	2016 - 2019 <b>Lecturer</b> Co-Teaching in the <b>Dynamic Systems</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	November 2012 - January 2013 <b>Lecturer</b> Co-Teaching in the <b>Dynamic Systems</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	September 2012 - December 2012 <b>Lecturer</b> Teaching <b>Fundamentals of Automation and Robotics</b> at the technical course IFTS "Tecnico superiore per l'automazione industriale" organized by Tuscany Region with D.D. 5253 of 24/11/2011 Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	January 2012 <b>Lecturer assistant</b> Teaching in the <b>Dynamic System</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	April 2011 - July 2011 <b>Lecturer assistant</b> Teaching in the <b>Control System Design</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	January 2011 - February 2011 <b>Lecturer assistant</b> Teaching in the <b>Dynamic System</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
Dates Occupation or position held Main activities Name and type of organization	March 2010 - June 2010 <b>Lecturer assistant</b> Teaching in the <b>Control System Design</b> class Department of Information Engineering and Mathematics, University of Siena, Italy
<b>Society memberships and Honors #4</b>	
IEEE ICRA 2024	Selected in the <b>New Generation Stars Program</b> , sponsored by NOKOV Motion Capture
Coordinator of Research Unit	From October 2023, <b>coordinator</b> of the University of Siena Unit for the Erasmus+ Project: ImmersiveSurgicalEdu - Beyond the classroom: Virtual Reality, Augmented Reality and Haptics for enhanced surgical training and education
Coordinator of Research Unit	From October 2023, <b>coordinator</b> of the University of Siena Unit for the MUR PRIN Project: ARTIS - Augmented Robotic Touch and hyperspectral Imaging Senses
Coordinator of Research Unit	From October 2020 to May 2023, <b>coordinator</b> of the University of Siena Unit for the Erasmus+ Project: AUGMENTWEAREDU - Integrating virtual and AUGMENTED reality with WEARable technology into engineering EDUCation.
Principal Investigator	From 2021 to 2023, <b>PI</b> for the project AROSE - Assistive RObotics for Safe interaction with the body, F-CUR project financed by the University of Siena.

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Activity Leader	From 2023, <b>Activity Leader</b> for the Activity A8, Mission 3 for the project Fit4MedRob, financed by the Italian Ministry of Research.																								
Teching body, “Collegio dei Docenti”	From October 2023 part of the ‘Collegio dei Docenti” for the PhD school in Smart Industry organised by University of Pisa, University of Florence and University of Siena.																								
Master Technical Committee	From October 2019 part of the Scientific Board for the First Level Master in “Industry 4.0 Design" organised by University of Pisa, University of Firenze and University of Siena.																								
ARTES 4.0	From January 2020 to May 2022 vice-responsible for the University of Siena of the <b>ARTES 4.0</b> consortium and referent for the Department of Information Engineering and Mathematics.																								
National Academic Qualification	From November 2023 qualified as <b>Full Professor</b>																								
Societies	<b>IEEE Senior Member</b> and RAS member, I-RIM																								
<b>Awards #5</b>																									
ICRA 2024	<b>Winner</b> of the IEEE ICRA 2024 Competition on Human-to-Robot Handovers																								
RO-MAN 2022	<b>Best RSJ Pioneering Research Award in Robot and Human Interactive Communication paper finalist</b> L. Franco, G. Salvietti, M. Pompilio, S. Rossi, D. Prattichizzo, On the Somatotopic Mapping of Haptic Feedback from Robotic Supernumerary Limbs																								
I-RIM 3D 2022	<b>Best Student Paper Award</b> , M. Dragusanu, S. Marullo, M. Malvezzi, G. Achilli, M. Valigi, D. Prattichizzo, G. Salvietti, Soft Collaborative Gripper for Dressing Assistance																								
INTAP 2021	<b>Best Conference Paper Award</b> , F. Sanfilippo, T. Blažauskas, M. Girdžiūna, A. Janonis, E. Kiudys and G. Salvietti. A Multi-Modal Auditory-Visual-Tactile e-Learning Framework																								
I4SDG 2021	<b>Best Student Paper Award</b> , G. Achilli, M. Valigi, G. Salvietti, M. Pozzi and D. Prattichizzo, M. Malvezzi. Underactuated Soft Grippers for Helping Humans in Harmful Works																								
I-RIM 3D 2020	<b>Finalist Best Mechanical Design of Robotic Systems</b> , M. Malvezzi, G. Salvietti, M. Valigi, Z. Iqbal, M. Pozzi and D. Prattichizzo. Design of Wearable Robotic Extra Fingers for Human Hand Augmentation																								
I-RIM 3D 2019	<b>Best oral presentation</b> , M. Pozzi, G. Salvietti, J. Bimbo, M. Malvezzi, D. Prattichizzo. The Closure Signature: a New Approach to Model Soft Robotic Hands.																								
Haptic Symposium 2016	<b>Best Demo Award</b> , G. Spagnoletti, I. Hussain, C. Pacchierotti, G. Salvietti, D. Prattichizzo. The hRing: a haptic interface for an extra robotic finger.																								
ICORR 2015	<b>Best Student Paper Finalist</b> , I. Hussain, G. Salvietti, L. Meli, C. Pacchierotti, D. Prattichizzo. Using the robotic sixth finger and vibrotactile feedback for grasp compensation in chronic stroke patients.																								
<b>Personal skills and competences #6</b>																									
Technical skills and competences	Develop of control strategies for robotic hands in autonomous and teleoperation scenarios. Develop and test of control systems and electronic circuits for assistive robotics and haptics. Control of robotic hand/arm systems as well as robotic mobile platforms.																								
Computer skills and competences	Deep knowledge of MAC OS X, LINUX and WINDOWS operative systems. Deep knowledge of L <sup>A</sup> T <sub>E</sub> X and Microsoft Office suite for word processing. Good CAD and Electronic spreadsheet skills. Programming languages known: Matlab, C++, C, Pascal, VHDL, PLC programming, V+. Optimal ability to retrieve information and documents from internet. Deep knowledge of IEEEExplore and Google Scholar tools for technical web searching.																								
Mother tongue(s)	<b>Italian</b>																								
Other language(s)																									
<i>Self-assessment European level(*)</i>																									
<b>English</b>	<table><tr><th colspan="2">Understanding</th><th colspan="2">Speaking</th><th rowspan="2">Writing</th></tr><tr><th>Listening</th><th>Reading</th><th>Spoken interaction</th><th>Spoken production</th></tr><tr><td>C1</td><td>C1</td><td>C1</td><td>C1</td><td>C1</td></tr><tr><td>A2</td><td>A2</td><td>A2</td><td>A2</td><td>A2</td></tr><tr><td>B1</td><td>B1</td><td>A2</td><td>A2</td><td>A2</td></tr></table>	Understanding		Speaking		Writing	Listening	Reading	Spoken interaction	Spoken production	C1	C1	C1	C1	C1	A2	A2	A2	A2	A2	B1	B1	A2	A2	A2
Understanding		Speaking		Writing																					
Listening		Reading	Spoken interaction		Spoken production																				
C1		C1	C1	C1	C1																				
A2	A2	A2	A2	A2																					
B1	B1	A2	A2	A2																					
<b>German</b>																									
<b>French</b>																									

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## Language certifications

P.E.T. Cambridge University – Final mark: pass with Merit  
Spoken English for Speakers of Other Languages Trinity College London – Final mark: grade 5, pass with Merit  
Vorgesaltete DaF-Kurse Hamburg University - DaF 9, Level A1.1/A1.2

## Conference and Workshop organization #7

I-RIM 3D 2022

I-RIM 3D 2022

Ro-Man 2022

I-RIM 3D 2020

ICNR 2018

IROS 2018

ICORR 2017

ICRA 2016

Ro-Man 2016

## Associate Editor #8

From 2022

From 2022

From 2021

From 2020

From 2016 to 2023

## Guest Editor in Special Issues in Journals

Frontiers in Robotics and AI, 2022

Frontiers in Robotics and AI, 2017

Robotic and Autonomous System, Elsevier, 2016

### Program Chair

**Grasping and Manipulation of Deformable Objects**, organised by G. Salvietti and M. Malvezzi

**TIGHT - Tactile InteGration for Humans and arTificial systems (III Edition)**, organised by M. Pozzi, T. Lisini Baldi, G. Salvietti, M. Bianchi, M. Malvezzi and D. Prattichizzo

**Two decades of rehabilitation and assistive robotics: lessons learned and future challenges**, organised by F. Cordella, A. Frisoli, S. Mazzoleni and G. Salvietti

**Artificial Supernumerary Limbs for Clinical Neuroscience**, organized by D. Prattichizzo and G. Salvietti

**User-centred methods in Human Robot Interaction**, organised by G. Salvietti, P. Beckerle and M. Bianchi

**Towards a next generation of wearable robotic devices for human-oriented assistance and therapy**, organised by G. Salvietti, W. Z. Rymer and E. van Asseldonk

**Exploiting contact and dynamics in manipulation**, organised by G. Salvietti, M. Malvezzi, D. Prattichizzo and O. Brock

**2nd Workshop on Human-Oriented Approaches for Assistive and Rehabilitation Robotics**, organised by P. Beckerle, G. Salvietti, R. Unal.

**IEEE Transaction on Robotics**

**IEEE ICRA Conference**

**IEEE IROS Conference**

**IEEE Transaction on Haptics**

**IEEE Robotics and Automation Letters**, International Conference on Rehabilitation Robotics (ICORR), Augmented Humans (AH)

**Robotic Grasping and Manipulation of Deformable Objects**, Guest Editors: M. Liarokapis, J. Bimbo, M. Malvezzi and G. Salvietti.

**Mapping Human Sensory-Motor Skills for Manipulation onto the Design and Control of Robots**, Guest Editors: M. Bianchi and G. Salvietti.

**Human-oriented Approaches for Assistive and Rehabilitation Robotics**, Special Issue Editors: P. Beckerle, G. Salvietti, R. Unal, F. Mastrogianni

## Collaboration to EU Integrated research projects #9

Main activities

Participation to the proposal preparation, organization and the realization of scientific activities with relative reports of the following EU co-founded research projects:

- **HARIA** - Human-Robot Sensorimotor Augmentation Coordinator of Workpackage on Design of Interfaces.
- **MAGICIAN** - iMmersive leArninG for ImperfeCtion detectIon and repAir through human- robot interactionN, Coordinator of Workpackage on Robotic platform and Interfaces.
- **REGO** - Cognitive robotic tools for human-centered small-scale multi-robot operations. Coordinator of Workpackage on High-level cognitive-based control and human-machine interfacing.
- **SoftPro** - Synergy-based Open-source Foundations and Technologies for Prosthetics and RehabilitatiOn. Coordinator of Workpackage on Extra-Limbs.
- **SOMA** - SOft MANipulation. Coordinator of Workpackage in Hand Control.
- **WEARHAP** - WEARable HAPTics for humans and robots. Coordinator of Workpackage on Cognitive Control of Wearable Haptic Systems.
- **THE** - The Hand Embodied.
- **ACTIVE** - Active Constraints Technologies for Ill-defined or Volatile Environments.
- **ROBOCAST** - ROBOt and sensor integration for Computer Assisted Surgery and Therapy.
- **HANDS.DVI** - A DeVice Independent programming and control framework for robotic HANDS) as part of the **ECHORD** experiment.

Name and type of organization

Department of Information Engineering and Mathematics, University of Siena and Department of Advanced Robotics and Human-Centred Mechatronics group, Istituto Italiano di Tecnologia, Italy

## Speaker at International Meetings #10

Invited Talks

Robotic Jam Session, University of Pisa (2023), FAU University, Erlangen, Germany (2022), University of Cataluña, Spain (2019), University of Lincoln, UK (2018), 19th International Organization of Psychophysiology (IOP) World Congress, Italy (2018), University of Southeast Norway, Norway (2018), University of Liege, Belgium (2017), University of Birmingham, UK (2017).

International Conferences

IEEE International Conference on Robotics and Automation (ICRA), IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Robotics, Science and Systems (RSS), IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN).

Talks in EU projects review  
meetings

INRIA, Rennes (France), University of Trento (Italy), OCADO Technology (UK), Twente University (Netherlands), TU Berlin (Germany), ETH Zurich (Swiss), University of Pisa (Italy), DLR (Germany), University Pierre e Marie Curie (France), University Rey Juan Carlos III (Spain), Istituto Italiano di Tecnologia (Italy).

## Activities as Reviewer #11

International Project Proposal  
Evaluator

Swiss National Science Foundation, Swiss (2023), Marsden Fund Proposal, New Zealand (2020). Strategic Basic Research Projects of the Research Foundation Flanders, European Science Foundation (2020)

Conference Program Committee

IEEE ICRA, Robotics, Science and System (RSS), IEEE BioRob, IEEE IROS, Augmented Humans

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International Journals	IEEE Transaction on Robotics, IEEE Robotics and Automation Magazine, IEEE Robotics and Automation Letters, International Journal on Robotic Research, Plos One, Advanced Robotics, IEEE/ASME Transaction on Mechatronics, IEEE Transaction on Haptics, Journal of Advanced Robotic System, Nature Scientific Reports, IEEE Access, Robotics, Applied Science, Sensors
International Conferences	IEEE International Conference on Robotics and Automation (ICRA), IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Robotics, Science and Systems (RSS), American Conference on Control (ACC), IEEE Conference on Decision and Control (CDC), IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN), IEEE International Conference on Biomedical Robotics and Biomechanics (BIOBIO), IEEE Conference on Robotics and Biomimetics (ROBIO), IEEE/RAS-EMBS International Conference on Rehabilitation Robotics (ICORR), International Symposium on Robotic Research (ISRR).
Social skills and competences	During my academic path I had the opportunity to work in collaboration with many colleagues and I learned how team-work can enhance the obtained results and speed-up the work-flow.
Organisational skills and competences	During my research as Assistant Professor I had the opportunity to organize and lead small research groups composed by Post-Doc and PhD students. I participated to the drafting of Milestones and Deliverables related to EU project research activities in collaboration with other research units.
<b>Work and Administration experience #12</b>	
Dates	October 2024
Occupation or position held	Docente
Main activities	Corso "Intelligenza artificiale nell'educazione" (10 h)
Name and address of employer	Istituto Comprensivo Monte San Savino
Dates	January 2025 - February 2025
Occupation or position held	Docente
Main activities	Corso "Intelligenza artificiale nell'educazione" (10 h)
Name and address of employer	Istituto Comprensivo Castiglion Fiorentino
Dates	May 2019 - today
Occupation or position held	Member of the city council for the municipality of Marciano della Chiana, Arezzo, Italy
Main activities	<b>"Assessore"</b> with the responsibility for Culture, Tourism, Innovation and School
Name and address of employer	Municipality of Marciano della Chiana, Italy.
Dates	May 2019 - today
Occupation or position held	Member of the city council for the municipality of Marciano della Chiana, Arezzo, Italy
Main activities	<b>"Assessore"</b> with the responsibility for Culture, Tourism, Innovation and School
Name and address of employer	Municipality of Marciano della Chiana, Italy.
Dates	February 2014 - April 2016
Occupation or position held	External consultant
Main activities	<b>Lecturer</b> , course on advanced technical writing
Name and address of employer	Estra S.p.A., Italy
Type of business or sector	Energy provider
Dates	June 2018
Main activities	Passed course on high risk environment
Name and address of employer	Università degli Studi di Siena, Italy
Dates	January 2001 - August 2003
Occupation or position held	External consultant
Main activities	Organization of musical and social events, organization of advertising campaigns
Name and address of employer	JWR Grandi Eventi S.r.l., Via della Stazione, 54/A 52048 - Monte S. Savino (Arezzo), Italy
Type of business or sector	Marketing, Management

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## Patents #13

- 1 D. Prattichizzo, G. Salvietti, I. Hussain, S. Rossi, G. Spagnoletti, D. Cioncoloni. A device for enhancing a user's grasping capability – The extra finger. National Patent N.102016000013321, 20.8.18. – International Application [pending] N.PCT/IB2017/050725, 17.8.17.
- 2 D. Prattichizzo, S. Marullo, G. Salvietti M. Z. Iqbal, S. Bartoccini, Sistema di presa con accoppiamento magnetico per la manipolazione robotica National Patent N.102020000019570, 06.8.2020

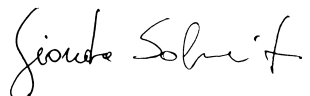
## Publications #14

Publication summary: 39 journal papers, 40 peer-reviewed conference papers. H-index: 28 (Scopus), 32 (Scholar). Citations: 2134 (Scopus), 2972 (Scholar)

Date

February 2025

Signature



Autorizzo il trattamento dei miei dati personali ai sensi del Decreto Legislativo 30 giugno 2003, n. 196 “Codice in materia di protezione dei dati personali”

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